



Power Supply24 VAC, ±20%, 50/60 Hz, 24 VDC, -10% / +20%Power consumption in operation3.5 WPower consumption in rest position2.5 WTransformer sizing6 VA (class 2 power source)Shaft Diameter1/21.05" round, centers on 3/4" with insert, 1.05" without insertElectrical Connection18 GA appliance cable, 3 ft [1 m], with 1/2" conduit connectorOverload Protectionelectronic throughout 095° rotationElectrical Protectionactuators are double insulatedOperating RangeDC 210 V, 420 mA w/ ZG-R01 (500 Ω, 1/4 W resistor)Input Impedance100 kΩ for DC 210 V (0.1 mA), 500 Ω for 420 mAPosition FeedbackDC 210 V, Max. 0.5 mAAngle of rotation95°, adjustable with mechanical end stop, 3595°Torque motor90 in-Ib [10 Nm]Direction of motion fail-safereversible with cw/ccw mountingPosition indicationMechanically, 520 mm strokeManual override5 mm hex crank (3/16" Allen), suppliedRunning Time (Motor)95 sRunning time fail-safe<20 s @ -4122°F [-2050°C], <60 s @ -22°F [-30°C]Ambient humiditymax.95% r.H., non-condensingAmbient temperature-40176°F [-4080°C]Storage temperature-40176°F [-4080°C]DisctionIP66, NEMA 4X, UL Enclosure Type 4XHousing materialPolycarbonateAgency ListingCULus acc. to UL60730-1A/-2-14, CAN/CSA E60730-1:02, CE acc. to 2004/108/ECNoise level, motor40 dB(A)Noise level, fail-	Technical Data	
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420 mAPosition FeedbackDC 210 V, Max. 0.5 mAAngle of rotation95°, adjustable with mechanical end stop, 3595°Torque motor90 in-lb [10 Nm]Direction of rotation motorreversible with built-in switchDirection of motion fail-safereversible with cw/ccw mountingPosition indicationMechanically, 520 mm strokeManual override5 mm hex crank (3/16" Allen), suppliedRunning Time (Motor)95 sRunning time fail-safe<20 s @ -4122°F [-2050°C], <60 s @ -22°F [-30°C]Ambient humiditymax. 95% r.H., non-condensingAmbient temperature-22122°F [-3050°C]Storage temperature-40176°F [-4080°C]Degree of ProtectionIP66, NEMA 4X, UL Enclosure Type 4XHousing materialPolycarbonateAgency ListingcULus acc. to UL60730-1A/-2-14, CAN/CSA E60730-1:02, CE acc. to 2004/108/ECNoise level, fail-safe62 dB(A)Servicingmaintenance-freeQuality StandardISO 9001	Input Impedance	
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E60730-1:02, CE acc. to 2004/108/ECNoise level, motor40 dB(A)Noise level, fail-safe62 dB(A)Servicingmaintenance-freeQuality StandardISO 9001	Agency Listing	-
Noise level, fail-safe 62 dB(A)   Servicing maintenance-free   Quality Standard ISO 9001		
Servicing     maintenance-free       Quality Standard     ISO 9001	Noise level, motor	40 dB(A)
Quality Standard ISO 9001	Noise level, fail-safe	62 dB(A)
	Servicing	maintenance-free
	Quality Standard	ISO 9001
		9.5 lb [4.3 kg]

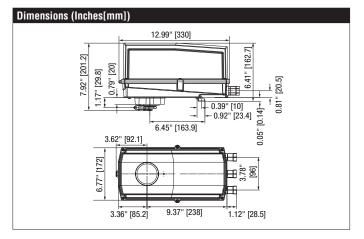
#### Torque min. 90 in-lb, for control of air dampers.

### Application

For modulation of dampers in HVAC systems. Actuator sizing should be done in accordance with the damper manufacturer's specifications. The actuator is mounted directly to a damper shaft up to 1.05" in diameter by means of its universal clamp. The actuator operates in response to a 2 to 10 VDC, with the addition of a 500 $\Omega$  resistor, a 4 to 20 mA control input from an electronic controller or positioner. A 2 to 10 VDC feedback signal is provided for position indication. Not to be used for a master-slave application.

### Operation

The NF.24-SR N4 series actuators provide true spring return operation for reliable fail-safe application and positive close off on air tight dampers. The spring return system provides constant torque to the damper with, and without, power applied to the actuator. The NF.24-SR N4 series provides 95° of rotation and is provided with a graduated position indicator showing 0° to 95°. The NF.24-SR N4 uses a brushless DC motor which is controlled by an Application Specific Integrated Circuit (ASIC) and a microprocessor. The microprocessor provides the intelligence to the ASIC to provide a constant rotation rate and to know the actuator's exact fail-safe position. The ASIC monitors and controls the brushless DC motor's rotation and provides a digital rotation sensing function to prevent damage to the actuator in a stall condition. The actuator may be stalled anywhere in its normal rotation without the need of mechanical end switches. The NF.24-SR N4 actuator is shipped at 5° (5° from full fail-safe) to provide automatic compression against damper gaskets for tight shut-off.



Safety Notes

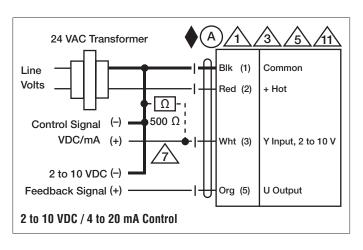
WARNING: For Belimo products sold in California: these products do or may contain chemicals which are known to the State of California to cause cancer and or birth defects or other reproductive harms. For more information see www.p65warnings.ca.gov.

†Rated Impulse Voltage 800V, Type of action 1.AA, Control Pollution Degree 4.



## NFB24-SR N4 Damper Actuator Technical Data Sheet NEMA 4, Modulating, Spring Return, 24 V, for DC 2...10 V or 4...20 mA Control Signal

Accessories	
AF-P	Anti-rotation bracket AF/NF.
KG10A	Ball joint
KH10	Damper crank arm
SH10	Push rod for KG10A ball joint (36" L, 3/8" diameter).
T00L-06	8 mm and 10 mm wrench.
T00L-07	13 mm wrench.
ZG-DC1	Damper clip for damper blade, 3.5" width.
ZG-DC2	Damper clip for damper blade, 6" width.
ZG-JSA-1	1" diameter jackshaft adaptor (11" L).
ZG-JSA-2	1-5/16" diameter jackshaft adaptor (12" L).
ZG-JSA-3	1.05" diameter jackshaft adaptor (12" L).
11097-00001	Gasket for cable gland (for NEMA 4 models).
43442-00001	Cable gland (for NEMA 4 models).
ADS-100	Analog to digital switch for modulating actuators.
IRM-100	Input rescaling module for modulating actuators.
P475	Shaft mount, non-Mercury aux. switch for 1/2" dia. shafts.
P475-1	Shaft mount, non-Mercury aux. switch for 1" dia. shafts.
PS-100	Actuator power supply and control simulator.
PTA-250	Pulse width modulation interface for modulating actuators.
SGA24	Positioners suitable for use with the modulating damper
	actuators LMA-SR, NMA-SR, SMA-SR and GMA-SR
SGF24	Positioners suitable for use with the modulating damper
70 001	actuators LMA-SR, NMA-SR, SMA-SR and GMA-SR
ZG-R01	4 to 20 mA adaptor, $500\Omega$ , $1/4$ W resistor w 6" pigtail wires.
ZG-R02	50% voltage divider kit (resistors with wires).
ZG-SGF	Mounting plate for SGF.
ZG-X40	120 to 24 VAC, 40 VA transformer.



## Typical Specification

Spring return control damper actuators shall be direct coupled type which require no crank arm and linkage and be capable of direct mounting to a jackshaft up to a 1.05" diameter. The actuator must provide modulating damper control in response to a 2 to 10 VDC or, with the addition of a  $500\Omega$  resistor, a 4 to 20 mA control input from an electronic controller or positioner. The actuators must be designed so that they may be used for either clockwise or counter clockwise fail-safe operation. Actuators shall use a brushless DC motor controlled by a microprocessor and be protected from overload at all angles of rotation. Run time shall be constant, and independent of torque. A 2 to 10 VDC feedback signal shall be provided for position feedback. Actuators with auxiliary switches must be constructed to meet the requirements for Double Insulation so an electrical ground is not required to meet agency listings. Actuators shall be cULus listed and have a 5 year warranty, and be manufactured under ISO 9001 International Quality Control Standards. Actuators shall be as manufactured by Belimo.

# NFB24-SR N4 Damper Actuator Technical Data Sheet NEMA 4, Modulating, Spring Return, 24 V, for DC 2...10 V or 4...20 mA Control Signal



# Wiring Diagrams MARNING! LIVE ELECTRICAL COMPONENTS! During installation, testing, servicing and troubleshooting of this

During installation, testing, servicing and troubleshooting of this product, it may be necessary to work with live electrical components. Have a qualified licensed electrician or other individual who has been properly trained in handling live electrical components perform these tasks. Failure to follow all electrical safety precautions when exposed to live electrical components could result in death or serious injury.

Meets cULus requirements without the need of an electrical ground connection.

Actuators with appliance cables are numbered.

A

/5

/7\

Provide overload protection and disconnect as required.

Actuators may also be powered by 24 VDC.

Only connect common to negative (-) leg of control circuits.

A 500  $\Omega$  resistor (ZG-R01) converts the 4 to 20 mA control signal to 2 to 10 VDC.

Actuators may be connected in parallel if not mechanically linked. Power consumption and input impedance must be observed.